Why Camera Calibration Using Variance Doesn't Work for Photoresponse Calibration of Scientific CMOS (sCMOS) Cameras (and Other Photodetectors)

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INTRODUCTION

A scientific camera should:

accurately detect the number of input photons,

Changing the Game

- faithfully represent the number of input photons in the digital output signal, and
- provide predictable noise statistics

sCMOS camera architecture fundamentally differs from CCD and EMCCD cameras. In scientific digital CCD and EMCCD cameras, conversion from charge to the digital output is generally through a single electronic chain, and the read noise and the conversion factor from photoelectrons to digital outputs is highly uniform for all pixels, although quantum efficiency may

LINEARITY

Linearity, low light range, 3 different cameras

a



TEMPORAL READOUT NOISE & VARIANCE MODEL

PHOTON

IS

OUR BUSINESS



Figure 5. Pixel-specific temporal dark read noise of ORCA-Flash4.0 V3

spatially vary.

By contrast, in CMOS cameras, the charge to voltage conversion is separate for each pixel, each column has independent amplifiers and analog-to-digital converters, and microlenses introduce pixel-to-pixel variation in quantum efficiency. The "raw" output from the CMOS image sensor includes pixel-topixel variability in the read noise, gain, offset and dark current. Therefore, scientific camera manufacturers digitally compensate the raw signal from the CMOS image sensors^{1, 2}. Inaccuracies and noise in images can introduce artifacts in computational imaging such as localization microscopy, especially in the case of maximum likelihood estimation methods^{3, 4}.

The Hamamatsu ORCA-Flash4.0 V3 has well-calibrated pixel response and predictable individual pixel statistics. We show that for this camera (peak QE, 82%):

- individual pixels are accurately factory-calibrated for dark offset and photo-response,
- Output is highly linear to input photons across the entire signal range, and
- individual pixel variance can be accurately modeled as a sum of two pixelspecific terms: read noise and a variance coefficient multiplied by the signal in the pixel (shot noise), however **pixel variance is not an** accurate method for calibration of pixel or camera gain.

DARK OFFSET & UNIFORMITY

ISNU. Dark Offset

DSNU, mean \pm 0.92 e⁻(2 DN)

Standard scan

50 x 50 pixels

С

b

Log-linear histogram of



Fractional error (%): based on EMVA1288 standard

amera_2	Camera_3	Camera_4
nearity error = 0.39%	Linearity error = 0.38%	Linearity error = 0.33%
nearity = 99.61%	Linearity = 99.62%	Linearity = 99.67%

Figure 3. Linearity of 3 different cameras in both a) low and b) high light ranges.



Figure 4. Distribution of absolute response error at various light levels

sCMOS camera.

a

b

Variance coefficient (K_{xv}) map Histogram of Variance coefficient (K_{xy}) 2.2 2.15 1 05 requency 1.9 1.95 2 2.05 2.1 2.15 2.2 2.25 DN²/DN

Variance_{xv} = K_{xv}^* (Signal_{xv}-Offset_{xv}) + readnoise²_{xv} K_{xv} estimation fit using weighted least square at 9 light level 20000 frames at each light level 2048 x 2048







SD = 0.61 DN = 0.28

CAN VARIANCE BE USED FOR ACCURATE GAIN **CALIBRATION?**

While the photon transfer curve⁵ technique is a good method to validate camera (and pixel) performance, it is not a reliable method for camera photo-response or gain calibration.



- The relationship between the variance and the mean for a photoelectron signal, $\sigma^2 = G \langle N \rangle$, where, G= camera gain and $\langle N \rangle$ = mean number of photoelectrons / measurement assumes i) perfect counting statistics and ii) all measurements are statistically independent of any other measurements. In practice, (analog) coupling between individual pixel measurements may be >10%.
- Many other noises contribute to the variance, including i) instability in the illumination, ii) excess noise (from electron multiplication processes in EMCCD and iCCD cameras), iii) read noise, and iv) electrical pickup, such as clockinduced charge.
- The conversion from photons to electrons (QE), and hence photoresponse, may vary from pixel to pixel (or camera to camera).

Figure 5. a) Variance coefficient map, b) histogram of variance coefficient K_{xy} and residual K_{xy} error as a function of light level. The curve labeled "Statistical measurement precision limit" shows the statistical uncertainty in measurement of the variance of a single pixel using 20,000 measurements arising solely from statistical considerations.

CONCLUSIONS

- Production ORCA-Flash4.0 V3 sCMOS cameras with on-board correction have low dark offset non-uniformity.
- Photoresponse uniformity is comparable to front-illuminated CCDs (0.25%) and better than back-illuminated image sensors (e.g. EMCCDs, ~1%) for narrowband illumination.
- The digital output accurately represents the input intensity (photons) for each pixel.
- Uniform response (DN / photon) requires compensation for both QE and electronic gain variation.
- Using variance to estimate the gain does not correct for PRNU because of QE variations and other factors
- Variance is not a reliable method for accurate photodetector gain calibration as measurements without verification of the photodetectors statistics. Although the PTC provides an estimate of the electronic "gain," the "photon transfer curve" method theory is based upon the statistical independence of each measurement, absence of excess noise,

Figure 1. DSNU a) map, b) offset histogram and c) threshold map of pixels > 2 DN (0.92 e^{-}) from the mean.

SD within mean \pm 0.92 e⁻ (2 DN) = 0.52 DN = 0.24 e⁻

Fraction within mean \pm 0.92 e⁻(2 DN) = 98.6 %

PHOTORESPONSE NON-UNIFORMITY







Log-linear histogram of pixel response under uniform illumination

Log-linear histogram of pixel response under uniform illumination



Figure 2. a) PRNU and b) log-linear histograms of pixel response uniformity in both low and high light ranges.

• Careful validation of the statistical model (including all noises) is required to extrapolate quantitative parameters from noise.

REFERENCES

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and no other noise sources., which is not generally correct.

ORCA-Flash4.0 V3 specification	
Dark Signal Non-Uniformity (DSNU) ¹	0.3 e⁻ rms
Photoresponse Non-Uniformity (PRNU) at half level of	0.06 % rms.
full light range (15,000 e ⁻) ¹	
Photoresponse Non-Uniformity (PRNU) at low light	0.3 % rms.
level (700 e ⁻) ¹	
Linearity error, full light range (EMVA 1288 standard) ¹	0.5 %
Linearity error, low light range (< 500 e ⁻ signal) ¹	0.2 % / Less than
	approx. 1 e-
	absolute error
Dark Current (electrons/pixel/s) – Air Cooled to -10° C	0.06
Readout Noise (N _r) median in electrons at slow scan ¹	0.8
Readout Noise (N _r) rms in electrons at slow scan ¹	1.4
Readout Noise (N _r) median in electrons at standard scan	1.0
1	
Readout Noise (N _r) rms in electrons at standard scan ¹	1.6

¹Typical value



